

USING A MOCK CATALOGUE TO IMPROVE GROUP FINDERS ALGORITHMS

MOCK CÓRDOBA- APRIL 10

FACUNDO RODRIGUEZ - MANUEL MERCHÁN





Introduction

- A common way to link observation with simulations is using galaxy groups as halos tracers.
- There are different group finders that recover different groups.
- The two most employed group finders are:
- Friends-Of-Friends.
- Halo-based group finder.



Friends-Of-Friends

Outline

- It is applied to select groups in a redshift survey, using only galaxy angular positions and observed redshifts.
- A pair of galaxies is linked if both their transverse and line-of sight separations are smaller than a specified pair of projected and line-of-sight linking lengths, respectively.
- It is an algorithm that links all galaxies that obey the linking condition to each other, thus yielding a unique catalogue galaxy groups.
- It is only based on an imposed overdensity and a correction factor for the distortion of the redshift space.
- E.g: Merchán, M. E., & Zandivarez, A. (2005). *Galaxy groups in the third data release of the sloan digital sky survey*. The Astrophysical Journal, 630(2), 759.



Friends-Of-Friends

Disadvantages

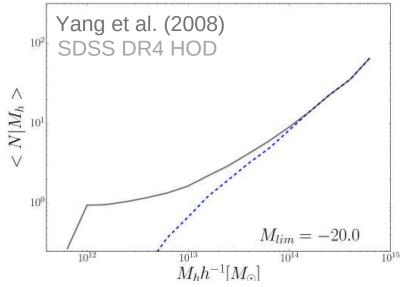
- It is not reliable for groups with few members $(N \ge 4)$.
- It has a lot of interlopers.
- It does not take into account galaxies luminosity to determine their membership to the groups.
- It tends to artificially merge the structures.
- It has a lot of completeness but many fake groups.
- It is not suitable for some studies (E.g Halo Occupation Distribution).



Friends-Of-Friends

Disadvantages

• It is not reliable for groups with few members $(N \ge 4)$.



• It is not suitable for some studies (E.g Halo Occupation Distribution).



Halo-based group finder

Outline

- It is iterative algorithms based on phase-space properties of dark matter haloes.
- It assumes that galaxies follow a spherical NFW profile as dark matter.
- Membership of galaxies is conditioned to their luminosities.
- All galaxy groups have at least one bright galaxy.
- Halo Mass estimation is part of the method and it is assigned using abundance matching on luminosity.
- E.g: Yang, X., Mo, H. J., Van Den Bosch, F. C., & Jing, Y. P. (2005). *A halo-based galaxy group finder: calibration and application to the 2dFGRS*. Monthly Notices of the Royal Astronomical Society, 356(4), 1293-1307.



Goal of this work

To improve the FOF algorithm incorporating the

halo definition of Halo - Based finders

Steps:

1. To perform a FOF by

applying luminosity constraints.

2. To improve it by applying the halo-based finders technique



Friends-Of-Friends

- We select groups following Huchra & Geller (1982) linking pairs of galaxies when the transverse (D_{12}) and line-of sight (V_{12}) separations are smaller than a specified projected and line-of-sight linking lengths.
- Linking lengths take into account the number density variation due to the apparent magnitude limit of the survey (R).

$$D_{12} = 2\sin\left(\frac{\theta_{12}}{2}\right) D \le D_L = D_0 R \qquad V_{12} = |V_1 - V_2| \le V_L = V_0 R$$

$$R = \left[\frac{\int_{-\infty}^{M_{12}} \phi(M) dM}{\int_{-\infty}^{M_{lim}} \phi(M) dM}\right]^{\frac{1}{2}}$$



Friends-Of-Friends Luminosity constraints

- We apply restrictions to the absolute magnitude of the galaxy members:
 - We consider only groups that have at least one bright galaxy.
 - We do not apply any restrictions on the number of members.
 - Add as potential groups bright not linked galaxies.



Halo-based group finder

- 1. Find potential group centers
 - It starts with tentative groups identified using the FOF method.
 - The centers of identified groups with two members or more are considered as potential centers.
 - All galaxies not yet linked to these groups, are also treated as tentative centers of potential groups.
- 2. Determine the characteristic luminosity of each tentative group.
 - The group's characteristic luminosity $(L_{19.5})$ is defined combining luminosity of all group members with $M_r \leq -19.5$.



Halo-based group finder

3. Estimate the mass, size, and velocity dispersion of the dark matter halo associated with each tentative group.

• Using the value of $L_{19.5}$ determined above and an assumption for the group mass-to-light ratio $(M_h/L_{19.5})$ a mass is assigned to each group.

(Abbundance matching)

• Using the halo mass, the halo radius (r) and the line-of-sight velocity dispersion (σ) are calculated.



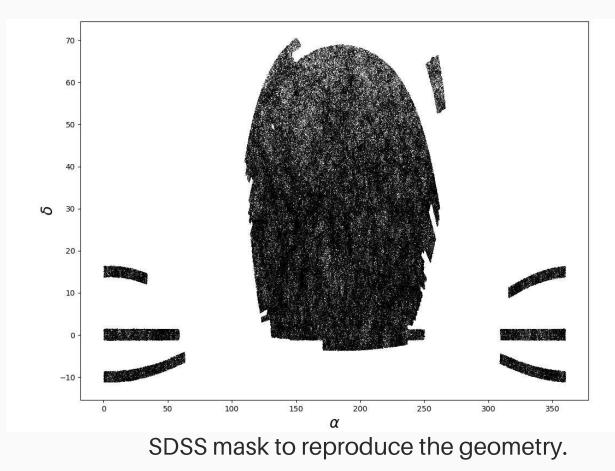
Halo-based group finder

- 4. Update group memberships using halo information.
 - It is assumed that the number density contrast of galaxies in the redshift space around the group center at redshift follows that of the dark matter.
 - It is defined $P_M(R, \Delta z)$ as the three-dimensional density contrast in redshift space and decide whether a galaxy should be assigned to a particular group if: $P_M(R, \Delta z) \ge B$

5. Iterate.

• This iteration process goes on until there is no further change in the group memberships.

Galaxy mock catalogue

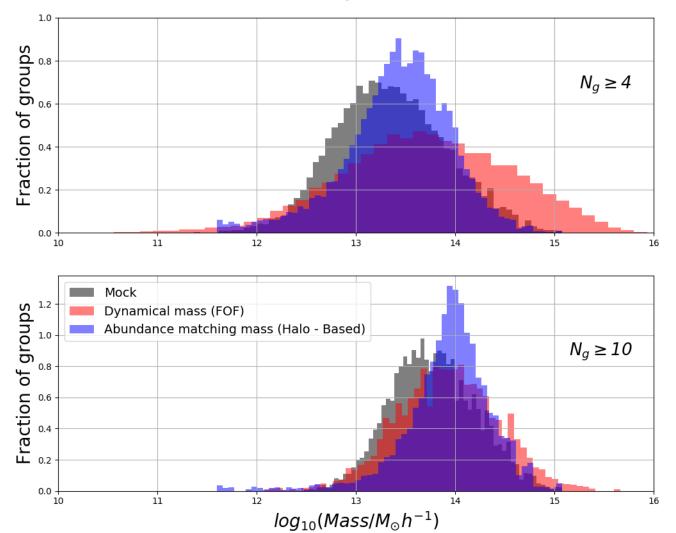


Semi-analytical model of galaxy formation (Guo et al. (2010)) applied on the Millennium I simulation (Springel et al., 2005).



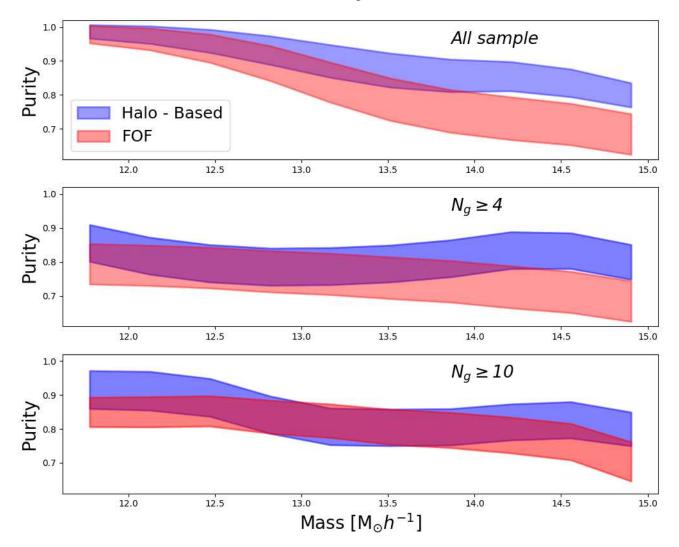


Mass comparison



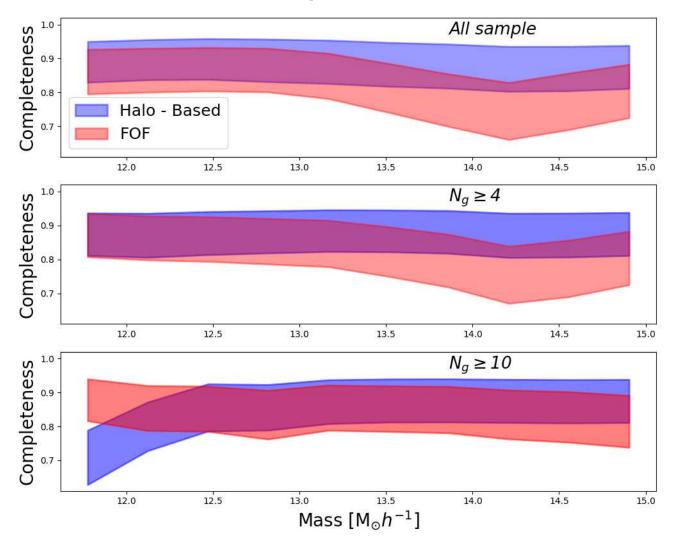


Purity



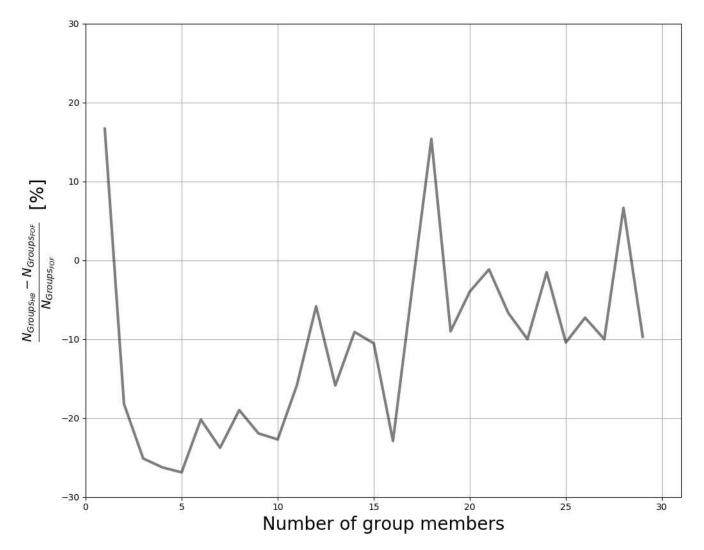


Completeness



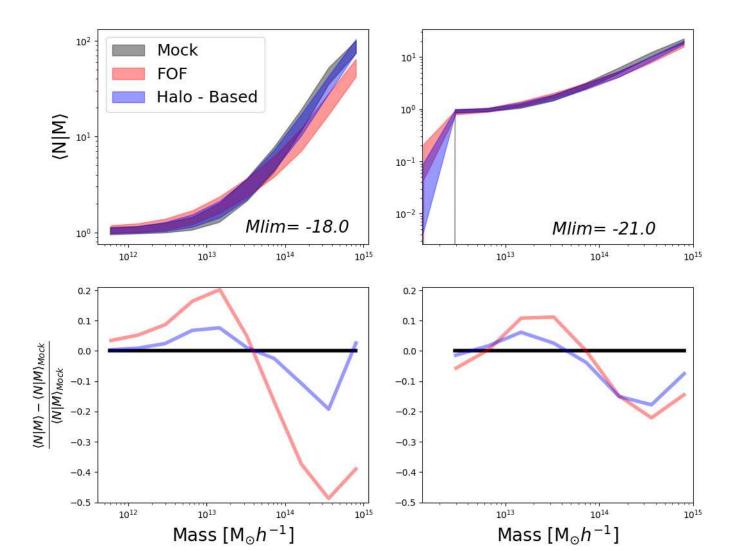


Ratio of the groups with the same number of members





Halo Occupation





Conclusions and future work

- We combined a full FOF algorithms with and Halo Based method to improve the group identification.
- Using a mock catalog to test our algorithms, we demonstrate the reliability of our groups.
- The next step is to implement this same procedure to obtain reliable groups in the SDSS.

Thanks for your attention!